

Geometry of ML estimation in Gaussian graphical models

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Motivation

Current statistical applications:

- Number of variables \gg Number of observations

- Example: Genetic networks

Gene expression data of a few individuals to model interaction between large number of genes

- ➔ **Gaussian graphical models** widely used in this context

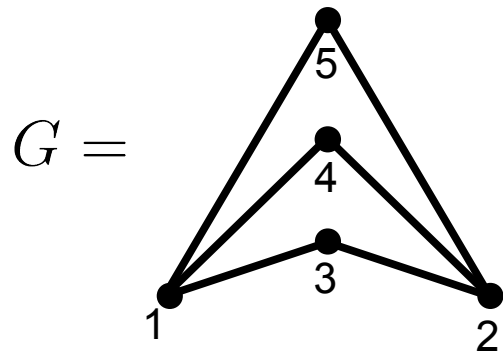
- ? Minimum number of observations for existence of MLE (maximum likelihood estimator) in Gaussian graphical model?

Gaussian graphical models

- $G = ([m], E)$ undirected graph with $(\alpha, \alpha) \in E \quad \forall \alpha \in [m]$.
- $X_1, \dots, X_n \in \mathbb{R}^m$ i.i.d. sample from $\mathcal{N}_m(0, \Sigma)$
- $\Sigma \in \mathbb{S}_{>0}^m$ covariance matrix on $[m]$ satisfying
 $(\Sigma^{-1})_{\alpha, \beta} = 0, \quad \forall (\alpha, \beta) \notin E.$
- $S := \frac{1}{n} \sum_{i=1}^n X_i X_i^T \in \mathbb{S}_{\geq 0}^m$ sample covariance matrix
- $S_G = (S_{\alpha, \beta} \mid (\alpha, \beta) \in E)$ sufficient statistics
- S_G **partial matrix** with entries at positions corresponding to edges E

Example $K_{2,3}$

- ➡ The Gaussian graphical model on $K_{2,3}$ consists of multivariate Gaussians satisfying



$$\Sigma^{-1} = \begin{pmatrix} \lambda_{11} & 0 & \lambda_{13} & \lambda_{14} & \lambda_{15} \\ 0 & \lambda_{22} & \lambda_{23} & \lambda_{24} & \lambda_{25} \\ \lambda_{13} & \lambda_{23} & \lambda_{33} & 0 & 0 \\ \lambda_{14} & \lambda_{24} & 0 & \lambda_{44} & 0 \\ \lambda_{15} & \lambda_{25} & 0 & 0 & \lambda_{55} \end{pmatrix}$$

- ➡ Given a sample covariance matrix S , the sufficient statistic is

$$S_G = \begin{pmatrix} s_{11} & ? & s_{13} & s_{14} & s_{15} \\ ? & s_{22} & s_{23} & s_{24} & s_{25} \\ s_{13} & s_{23} & s_{33} & ? & ? \\ s_{14} & s_{24} & ? & s_{44} & ? \\ s_{15} & s_{25} & ? & ? & s_{55} \end{pmatrix}$$

MLE, a special PD completion

Theorem (*Dempster, 1972*):

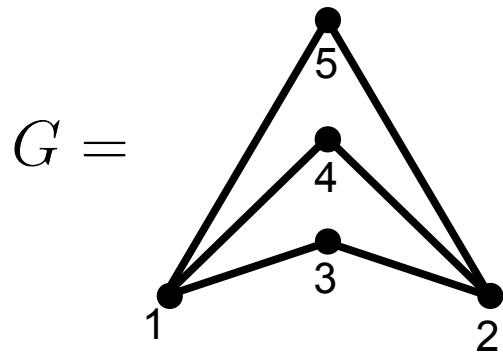
In a Gaussian graphical model on G the MLE $\hat{\Sigma}$ exists, if and only if the partial sample covariance matrix S_G can be completed to a positive definite matrix.

Then the MLE $\hat{\Sigma}$ is the unique completion, whose inverse satisfies

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- ➡ Existence of MLE in Gaussian graphical models is special **PD matrix completion problem** with rank constraint given by the number of observations.

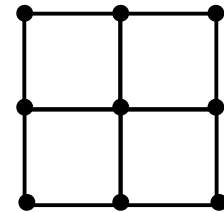
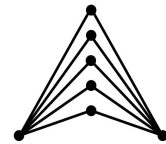
Outline

- Geometry of Dempster's theorem

- ➔ Characterization of minimal number of observations needed

- Examples

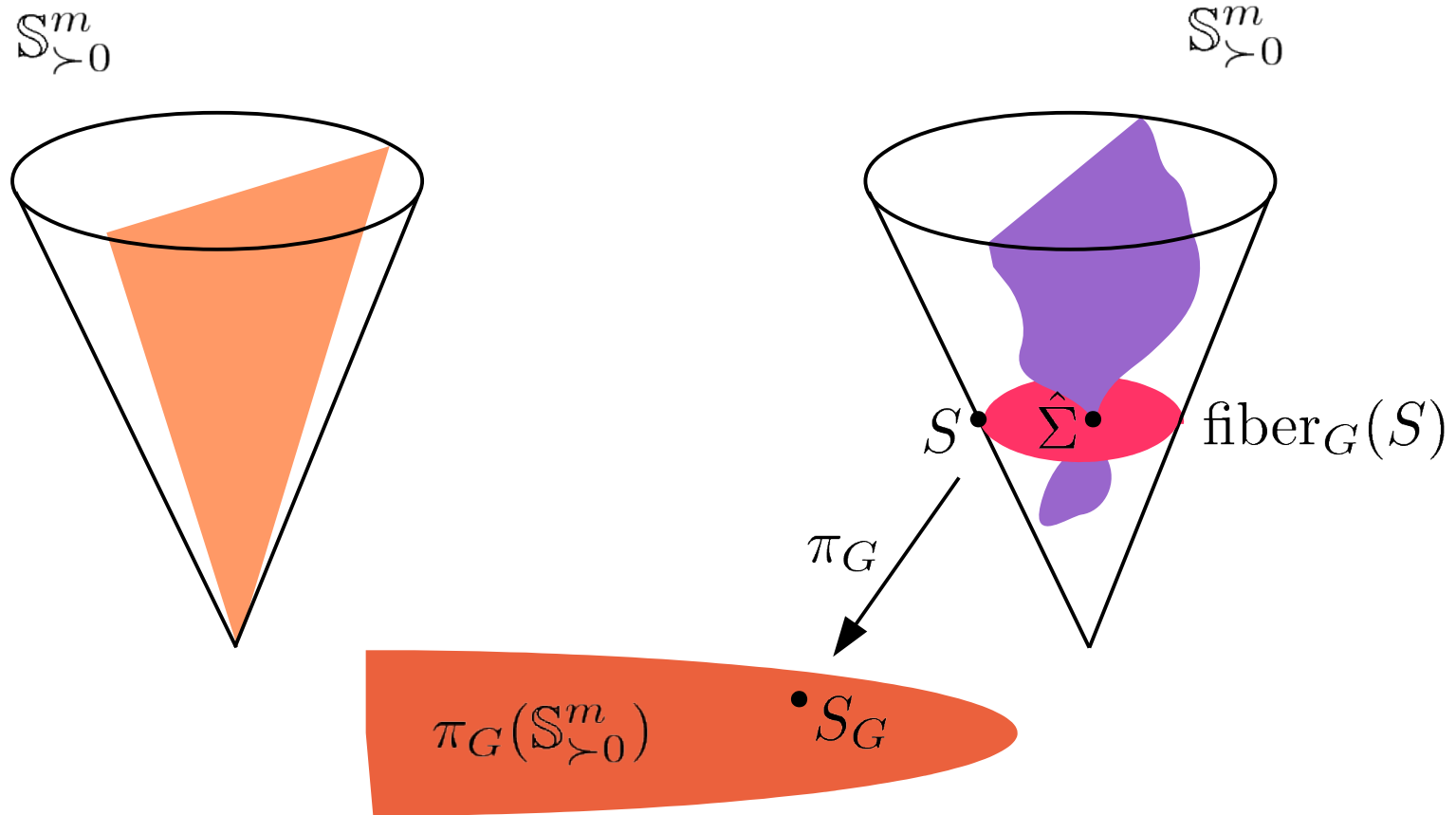
- Bipartite graphs $K_{2,m}$
 - 3-by-3 grid



Geometry of Dempster's theorem

Concentration matrices: $K = \Sigma^{-1}$

Covariance matrices: Σ



$$\text{fiber}_G(S) := \{\Sigma \in S_{>0}^m \mid \Sigma_G = S_G\}$$

Cones

Def: $\mathcal{C} \subset \mathbb{R}^k$ is a **convex cone** if

$$ax + by \in \mathcal{C} \quad \text{for all } a, b \geq 0, x, y \in \mathcal{C}.$$

Ex: $\mathbb{R}_+^m, \mathbb{S}_{\succeq 0}^m$

• **Cone of concentration matrices:** $\mathcal{K}_G := \mathcal{G} \cap \mathbb{S}_{\succeq 0}^m$

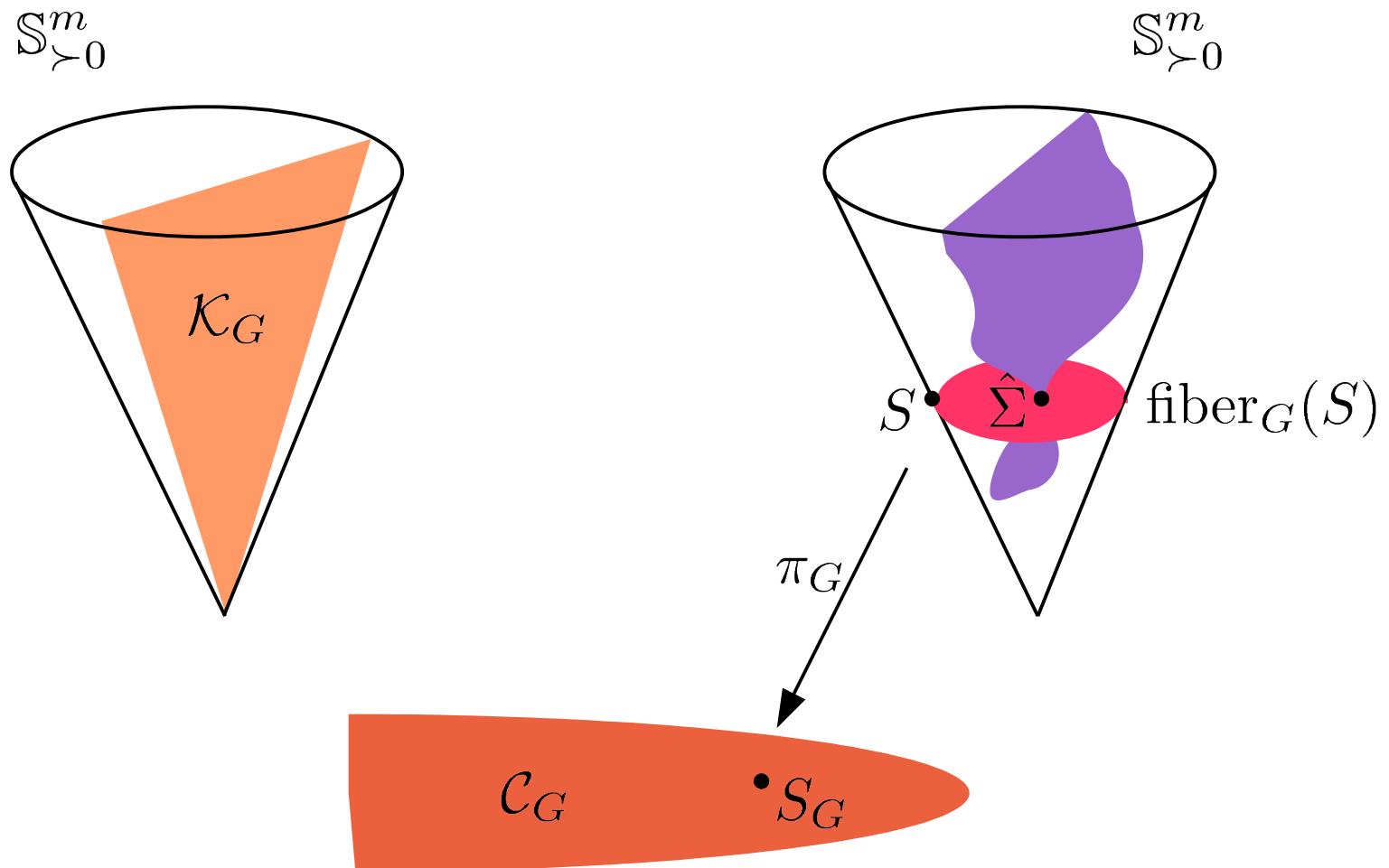
• **Cone of sufficient statistics:** $\mathcal{C}_G := \pi_G(\mathbb{S}_{\succeq 0}^m)$

where $\pi_G : \mathbb{S}^m \rightarrow \mathbb{R}^E, S \mapsto S_G$

Geometry of ML estimation

Concentration matrices: $K = \Sigma^{-1}$

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Cones and maximum likelihood estimation

Def: Let \mathcal{C} be a convex cone. The **dual cone** is

$$\mathcal{C}^* = \{w \mid \langle v, w \rangle \geq 0 \text{ for all } v \in \mathcal{C}\}.$$

Ex: \mathbb{R}_+^m , $\mathbb{S}_{\geq 0}^m$ are self-dual

Theorem (Sturmfels & U., 2010):

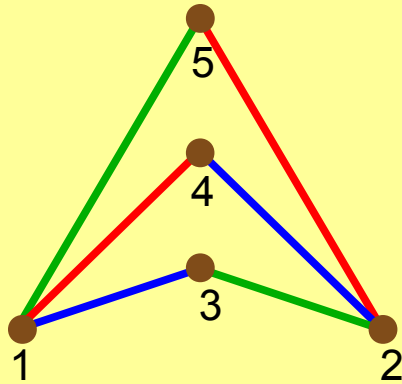
\mathcal{C}_G is the convex dual to \mathcal{K}_G . Furthermore, $\overline{\mathcal{K}_G}$ and $\overline{\mathcal{C}_G}$ are closed convex cones which are dual to each other with

$$\overline{\mathcal{K}_G} = \mathcal{G} \cap \mathbb{S}_{\geq 0}^m \quad \text{and} \quad \overline{\mathcal{C}_G} = \pi_G(\mathbb{S}_{\geq 0}^m).$$

- ➡ Used this duality to find an algebraic characterization of the cone of sufficient statistics

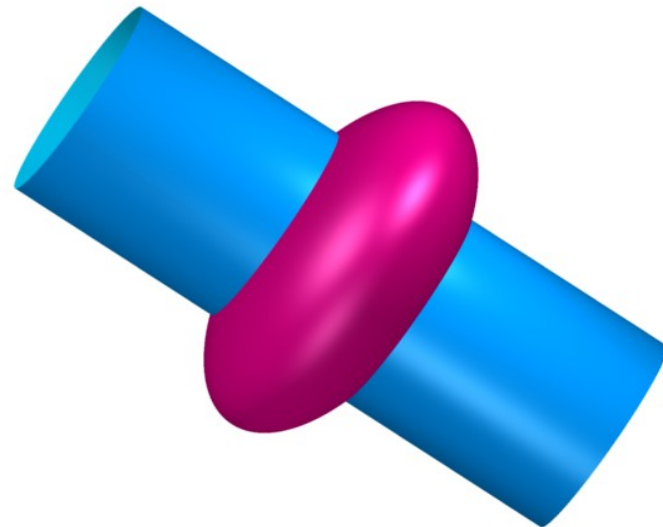
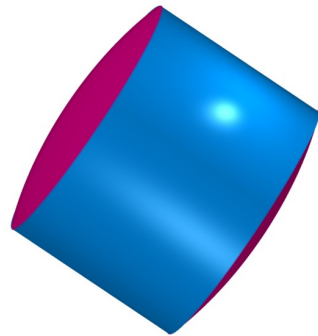
Example $K_{2,3}$

Example:



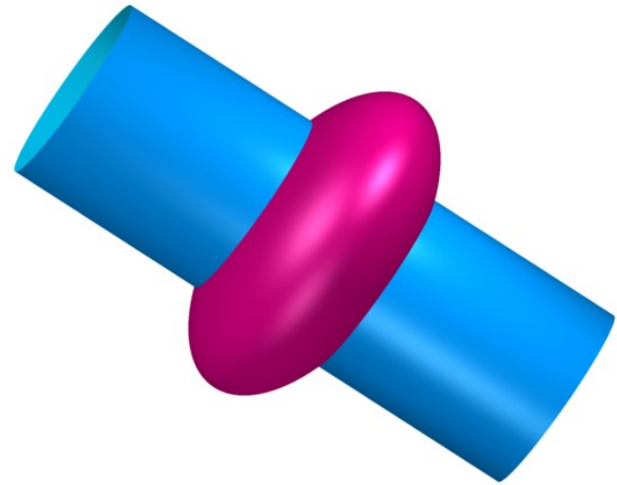
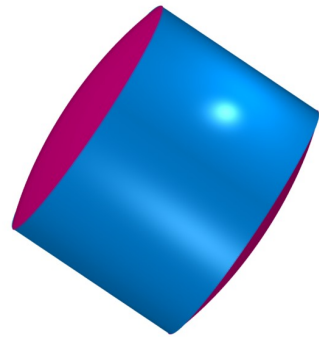
$$K = \begin{pmatrix} \lambda_1 & 0 & \lambda_2 & \lambda_3 & \lambda_4 \\ 0 & \lambda_1 & \lambda_4 & \lambda_2 & \lambda_3 \\ \lambda_2 & \lambda_4 & \lambda_1 & 0 & 0 \\ \lambda_3 & \lambda_2 & 0 & \lambda_1 & 0 \\ \lambda_4 & \lambda_3 & 0 & 0 & \lambda_1 \end{pmatrix}$$

$\mathcal{K}_G :$

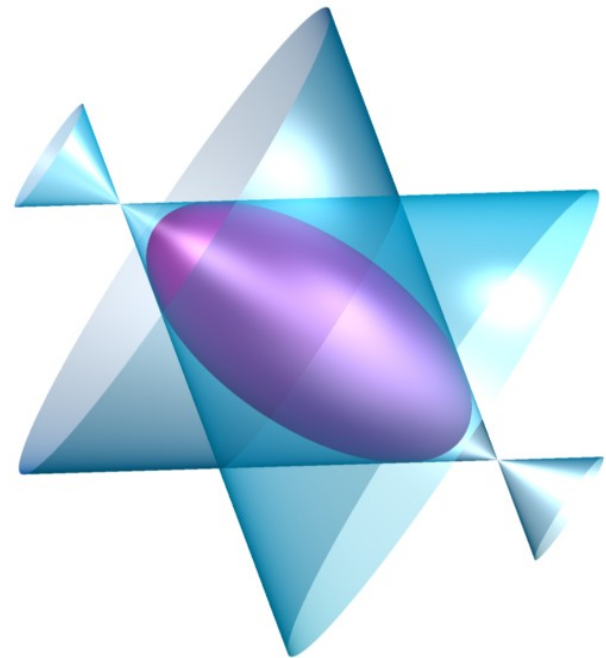


Example $K_{2,3}$

$\mathcal{K}_G :$



$\mathcal{C}_G :$



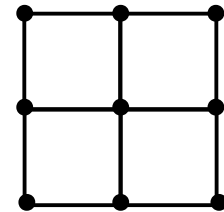
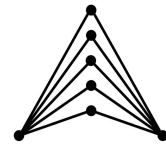
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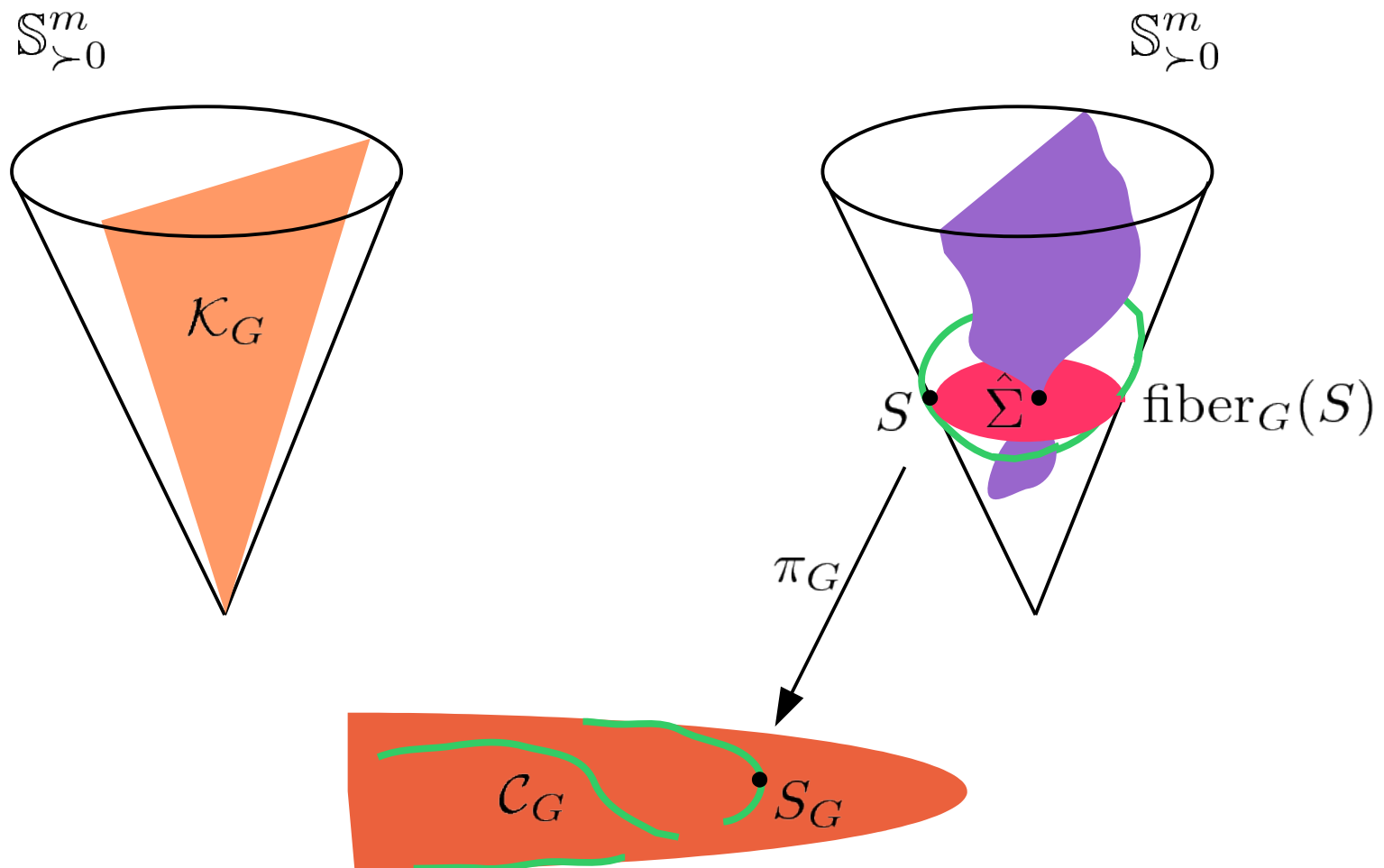
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Geometry of ML estimation

Concentration matrices: $K = \Sigma^{-1}$ Covariance matrices: Σ



Sufficient condition for existence of MLE

Elimination Criterion (U. 2010):

Let I_n be the ideal of $(n + 1) \times (n + 1)$ minors of a symmetric $m \times m$ matrix of unknowns S . Let $I_{G,n}$ be the elimination ideal obtained from I_n by eliminating all unknowns corresponding to non-edges in the graph. If

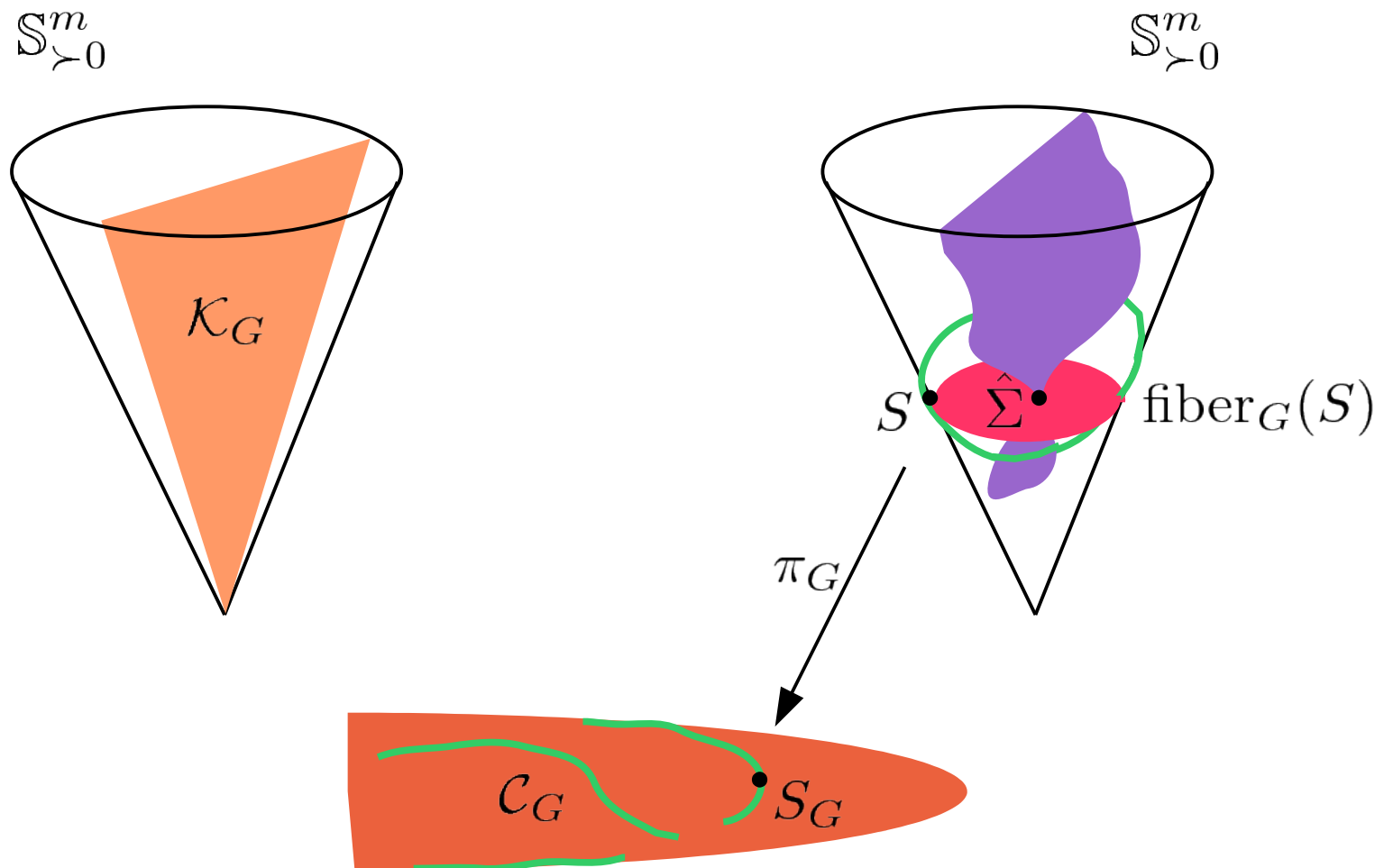
$$I_{G,n} = 0,$$

then the MLE exists with probability 1 for n observations.

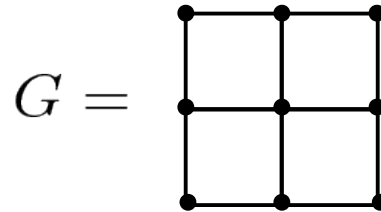
- ◆ I_n corresponds to all symmetric matrices of rank $\leq n$
- ◆ Elimination corresponds to projection onto \mathcal{C}_G
- ◆ $I_{G,n} = 0$ means that the projection is full-dimensional

Geometry of ML estimation

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3-by-3 grid



Theorem (U. 2010):

The MLE on the 3-by-3 grid exists with probability 1 if $n \geq 3$ and does not exist if $n = 1$. For $n = 2$ the MLE exists with probability $\in (0, 1)$.

Solves Steffen Lauritzen's open problem

- Sturmfels & U.: Multivariate Gaussians, semidefinite matrix completion, and convex algebraic geometry (AIMS 62, 2010)
- U.: Geometry of maximum likelihood estimation in Gaussian graphical models (submitted, arXiv:1012.2643v1)

Thank you!

- I am looking for a postdoc starting in September 2012 at the Institute of Science and Technology Austria.